



**Universidade Federal de Uberlândia
Engenharia Eletrônica e de Telecomunicações**

**- Processamento digital de sinais –
Capítulo 6 – Transformada z**

Prof. Alan Petrônio Pinheiro

A transformada z

- O que é uma transformada ?
- Domínio z (plano z complexo)
 - caracterização, estabilidade

- Definição:
$$X(z) \equiv \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

- Transformada inversa

$$x(n) \leftrightarrow X(z)$$



- Região de convergência (ROC ou RDC)
 - Valores de z para os quais $X(z)$ tem valor finito
- Exemplo: calcule a transformada z dos sinais

$$x_1(n) = \{1, 2, 3, 7, 0, 1\}$$

$$x_2(n) = \{1, 2, 3, 7, 0, 1\}$$

$$x_3(n) = \delta(n)$$

$$x_4(n) = \delta(n - k)$$

$$x_5(n) = \left(\frac{1}{2}\right)^n u(n)$$



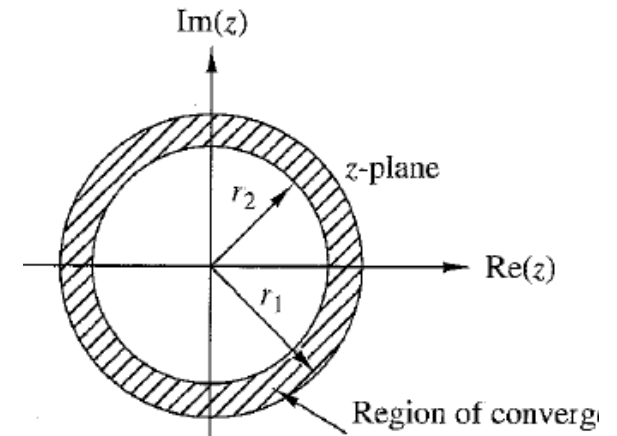
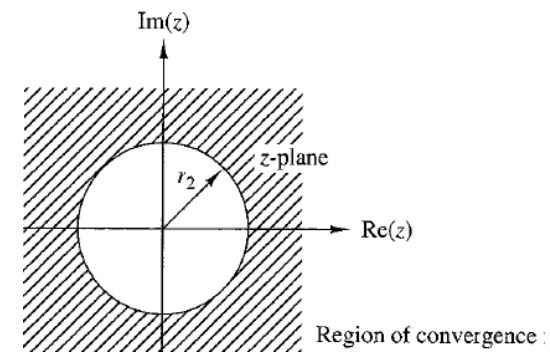
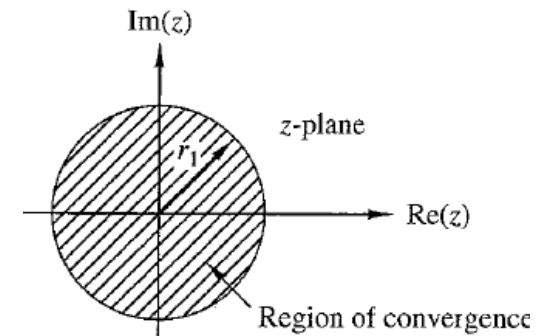
- Considere z como: $z = re^{j\theta}$

$$e \quad X(z)|_{z=re^{j\theta}} = \sum_{n=-\infty}^{\infty} x(n)r^{-n}e^{-j\theta n}$$

$$e \quad |X(z)| = \sum_{n=-\infty}^{\infty} |x(n)r^{-n}|$$

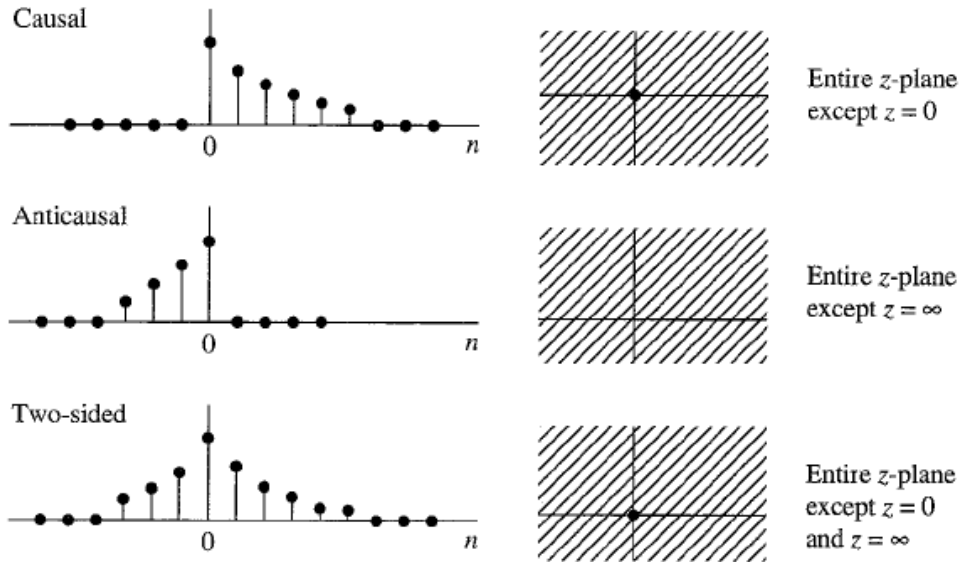
$$= \sum_{n=-\infty}^{-1} |x(n)r^{-n}| + \sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right|$$

$$= \sum_{n=1}^{\infty} |x(-n)r^n| + \sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right|$$

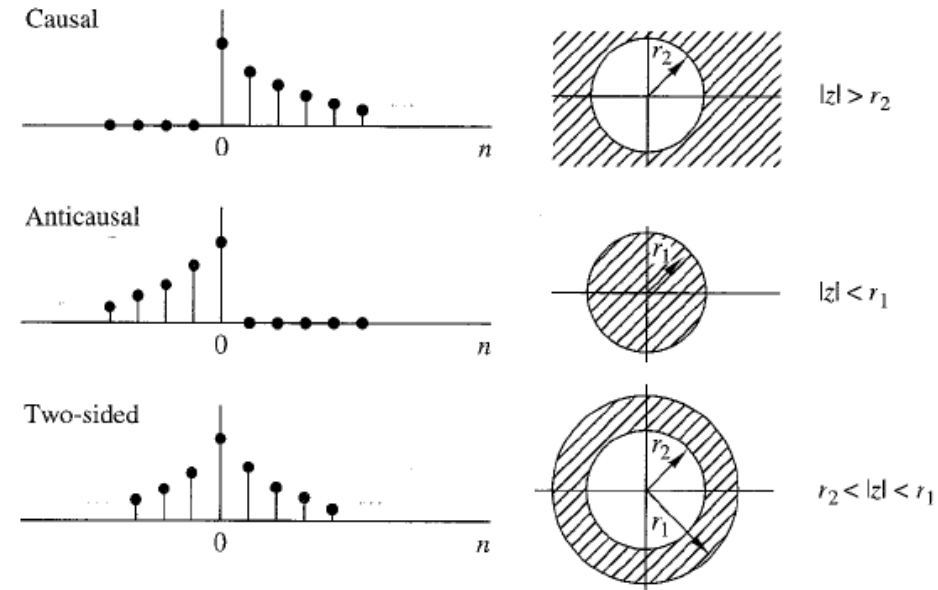


Signal ROC

Finite-Duration Signals



Infinite-Duration Signals



- Propriedades da transformada z

P.1) Linearidade

$$x(n) = a_1x_1(n) + a_2x_2(n) \leftrightarrow X(z) = a_1X_1(z) + a_2X_2(z)$$

Exemplo: determine a transformada z do sinal

$$x(n) = [3(2^n) - 4(3^n)]u(n)$$



P.2) Deslocamento no tempo

$$x(n) \leftrightarrow X(z)$$

$$x(n-k) \leftrightarrow z^{-k} X(z)$$

P.3) Escala no domínio z

$$x(n) \leftrightarrow X(z)$$

$$ROC : r_1 < |z| < r_2$$

$$a^n x(n) \leftrightarrow X(a^{-1}z)$$

$$ROC : |a| r_1 < |z| < |a| r_2$$



P.4) Diferenciação no domínio z

$$x(n) \leftrightarrow X(z)$$
$$nx(n) \leftrightarrow -z \frac{dX(z)}{dz}$$

P.5) Convolução de duas sequências

$$x_1(n) \leftrightarrow X_1(z)$$

$$x_2(n) \leftrightarrow X_2(z)$$

$$x(n) = x_1(n) * x_2(n) \leftrightarrow X(z) = X_1(z)X_2(z)$$

$$x(n) = Z^{-1}\{X(z)\}$$



Property	Time Domain	z -Domain	ROC
Notation	$x(n)$	$X(z)$	ROC: $r_2 < z < r_1$
	$x_1(n)$	$X_1(z)$	ROC ₁
	$x_2(n)$	$X_2(z)$	ROC ₂
Linearity	$a_1x_1(n) + a_2x_2(n)$	$a_1X_1(z) + a_2X_2(z)$	At least the intersection of ROC ₁ and ROC ₂
Time shifting	$x(n - k)$	$z^{-k}X(z)$	That of $X(z)$, except $z = 0$ if $k > 0$ and $z = \infty$ if $k < 0$
Scaling in the z -domain	$a^n x(n)$	$X(a^{-1}z)$	$ a r_2 < z < a r_1$
Time reversal	$x(-n)$	$X(z^{-1})$	$\frac{1}{r_1} < z < \frac{1}{r_2}$
Conjugation	$x^*(n)$	$X^*(z^*)$	ROC
Real part	$\text{Re}\{x(n)\}$	$\frac{1}{2}[X(z) + X^*(z^*)]$	Includes ROC
Imaginary part	$\text{Im}\{x(n)\}$	$\frac{1}{2}j[X(z) - X^*(z^*)]$	Includes ROC
Differentiation in the z -domain	$nx(n)$	$-z \frac{dX(z)}{dz}$	$r_2 < z < r_1$
Convolution	$x_1(n) * x_2(n)$	$X_1(z)X_2(z)$	At least, the intersection of ROC ₁ and ROC ₂
Correlation	$r_{x_1x_2}(l) = x_1(l) * x_2(-l)$	$R_{x_1x_2}(z) = X_1(z)X_2(z^{-1})$	At least, the intersection of ROC of $X_1(z)$ and $X_2(z^{-1})$
Initial value theorem	If $x(n)$ causal	$x(0) = \lim_{z \rightarrow \infty} X(z)$	
Multiplication	$x_1(n)x_2(n)$	$\frac{1}{2\pi j} \oint_C X_1(v)X_2\left(\frac{z}{v}\right)v^{-1}dv$	At least, $r_{1l}r_{2l} < z < r_{1u}r_{2u}$
Parseval's relation	$\sum_{n=-\infty}^{\infty} x_1(n)x_2^*(n)$	$= \frac{1}{2\pi j} \oint_C X_1(v)X_2^*(1/v^*)v^{-1}dv$	



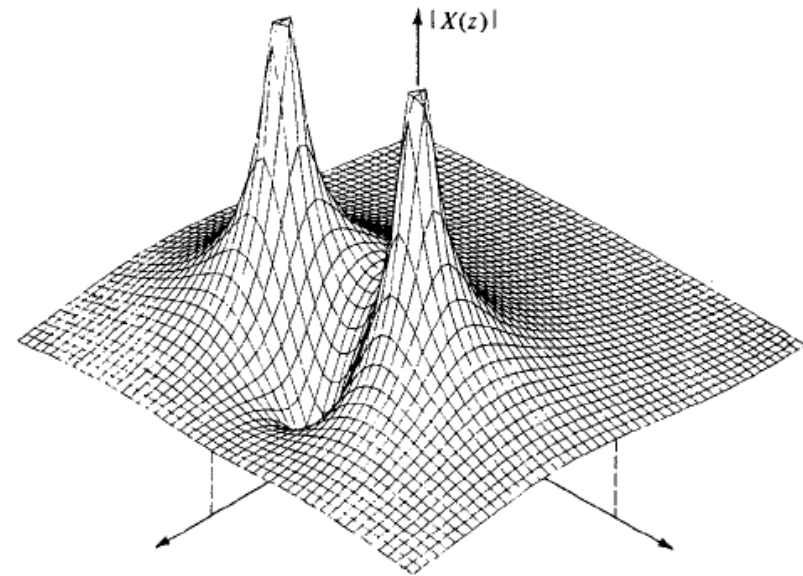
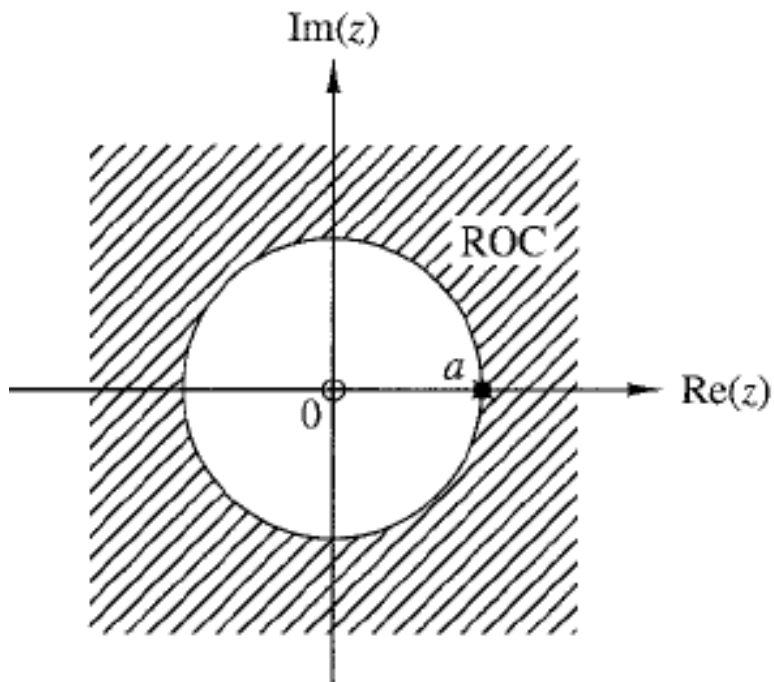
	Signal, $x(n)$	z -Transform, $X(z)$	ROC
1	$\delta(n)$	1	All z
2	$u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
3	$a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $
4	$na^n u(n)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
5	$-a^n u(-n - 1)$	$\frac{1}{1 - az^{-1}}$	$ z < a $
6	$-na^n u(-n - 1)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z < a $
7	$(\cos \omega_0 n)u(n)$	$\frac{1 - z^{-1} \cos \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$	$ z > 1$
8	$(\sin \omega_0 n)u(n)$	$\frac{z^{-1} \sin \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$	$ z > 1$
9	$(a^n \cos \omega_0 n)u(n)$	$\frac{1 - az^{-1} \cos \omega_0}{1 - 2az^{-1} \cos \omega_0 + a^2 z^{-2}}$	$ z > a $
10	$(a^n \sin \omega_0 n)u(n)$	$\frac{az^{-1} \sin \omega_0}{1 - 2az^{-1} \cos \omega_0 + a^2 z^{-2}}$	$ z > a $



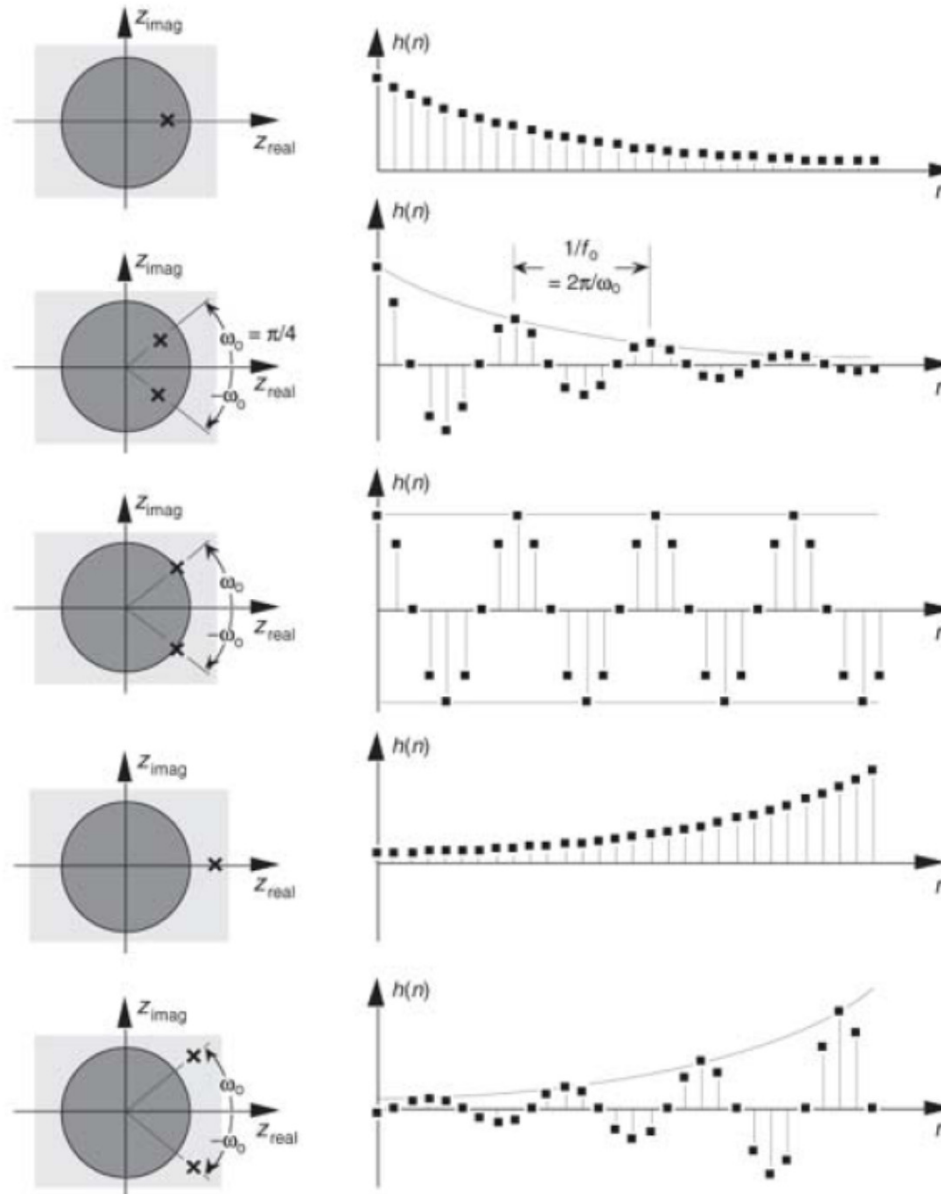
- Polos e zeros

$$X(z) = \frac{B(z)}{A(z)} = \frac{b_0 + b_1 z^{-1} + \dots + b_M z^{-M}}{a_0 + a_1 z^{-1} + \dots + a_M z^{-M}}$$

$$X(z) = \frac{B(z)}{A(z)} = \frac{b_0}{a_0} z^{-M+N} \frac{(z - z_1)(z - z_2) \dots (z - z_M)}{(z - p_1)(z - p_2) \dots (z - p_N)}$$

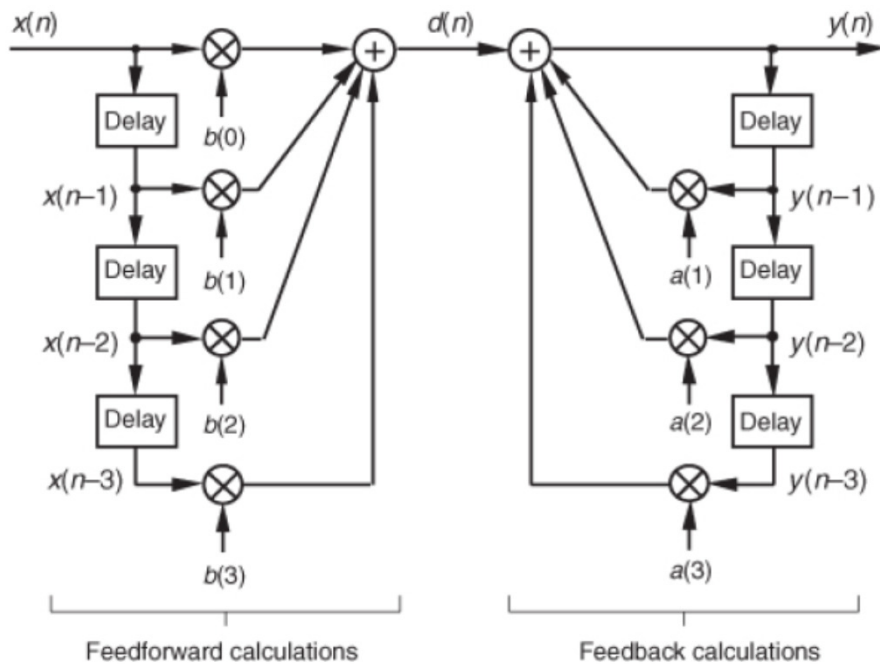


- Comportamento dos sinais



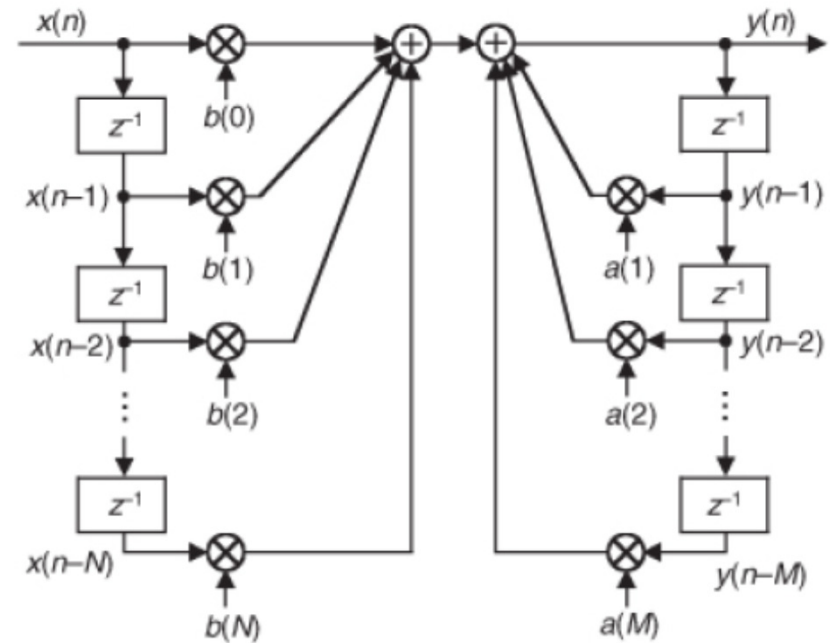
Análise de filtros IIR por Z

- Modelo:



(6-2)

$$y(n) = b(0)x(n) + b(1)x(n-1) + b(2)x(n-2) + b(3)x(n-3) + a(1)y(n-1) + a(2)y(n-2) + a(3)y(n-3).$$



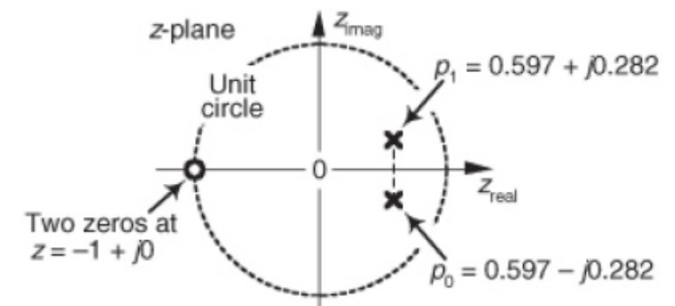
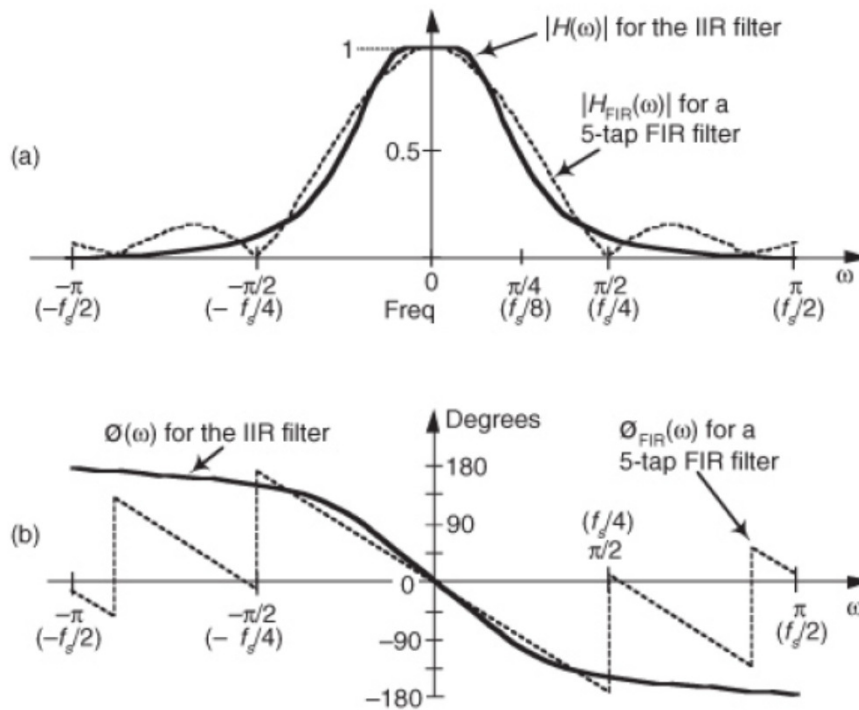
$$Y(z) = b(0)X(z) + b(1)X(z)z^{-1} + b(2)X(z)z^{-2} + \dots + b(N)X(z)z^{-N} + a(1)Y(z)z^{-1} + a(2)Y(z)z^{-2} + \dots + a(M)Y(z)z^{-M}$$



- Eq. Geral:

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^N b(k)z^{-k}}{1 - \sum_{k=1}^M a(k)z^{-k}}$$

- Exemplo 1: $y(n] = 0.0605 \cdot x(n] + 0.121 \cdot x(n-1] + 0.0605 \cdot x(n-2] + 1.194 \cdot y(n-1] - 0.436 \cdot y(n-2]$.



... Fatorando:

$$H(z) = \frac{(z - z_0)(z - z_1)}{(z - p_0)(z - p_1)} = \frac{(z + 1)(z + 1)}{(z - 0.597 + j0.282)(z - 0.597 - j0.282)}$$

